# mipi<sup>®</sup> DEVCON

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**MIPI I3C<sup>™</sup> Interface – Advanced Features** 

# HSINCHU CITY, TAIWAN

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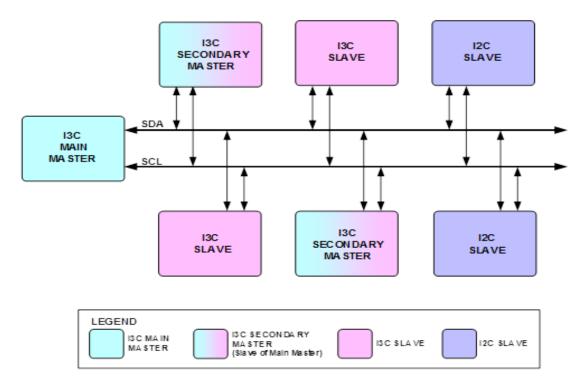


# Outline

- MIPI I3C<sup>™</sup> intelligent multifeatured interface
- List of main bus management procedures
- Timing Control
  - Problems solved, Challenges, Practical implementation aspects
- Elements of flow control
  - Problems solved, Challenges, Practical implementation aspects



### MIPI I3C<sup>™</sup> Bus Clients





# **MIPI I3C<sup>™</sup> – Intelligent Multifeatured Interface**

- MIPI I3C<sup>™</sup> supports several communication formats, all sharing a two-wire interface.
  - The two wires are designated SDA and SCL:
    - SDA (Serial Data) is a bidirectional data pin
    - SCL (Serial Clock) can be either a clock pin or a data pin while in certain HDR Modes
- An MIPI I3C<sup>™</sup> Bus supports the mixing of various Message types:
  - I<sup>2</sup>C-like SDR Messages, with SCL clock speeds up to 12.5MHz
  - Broadcast and Direct Common Command Code (CCC) Messages that allow the Master to communicate to all
    or one of the Slaves on the I3C Bus, respectively
  - HDR Mode Messages, which achieve higher data rates per equivalent clock cycle
  - I<sup>2</sup>C Messages to Legacy I<sup>2</sup>C Slaves
  - Slave-initiated requests to the Master, for example for In-Band Interrupt or to request the Master role



# **MIPI I3C<sup>™</sup> BUS Management Features**

- Dynamic Address Assignment
- Hot-Join
- In-Band Interrupt
- Secondary Master
- In-Band Hard RESET
- Timing Control
- Common Command Codes
- Error detection and Recovery
- Elements of Flow Control

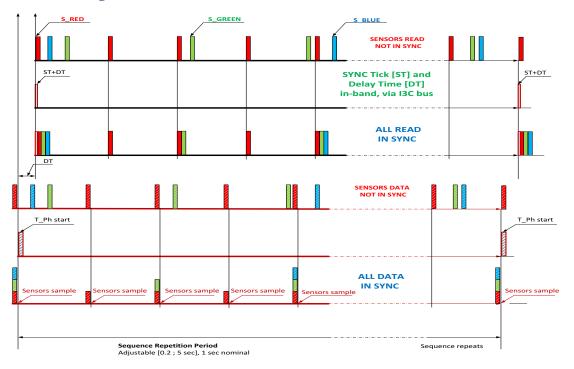


# **Timing Control**

- Complex applications require several Sensors on a common timeline
- Synchronous Systems and Events
  - Controlling the sampling moments has the potential of drastically reducing the system energy expenditure
- Asynchronous Systems and Events
  - The accuracy of the timestamps of events matters
- The Synchronous and Asynchronous modes can be used independently and concurrently on the same bus and devices

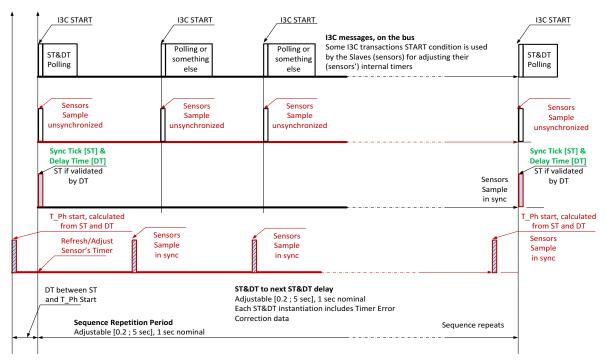


### **Synchronous Systems and Events**





### **Synchronous – Multiple Transactions**





# Synchronous – Common Command Codes

- SETXTIME CCC
- Configuration messages
  - ODR (Output Data Rate)
  - TPH (Procedure Repetition Time)
  - TU (Time Unit)
- Run Time messages
  - SYNC Tick [ST]
  - Delay Time [DT]

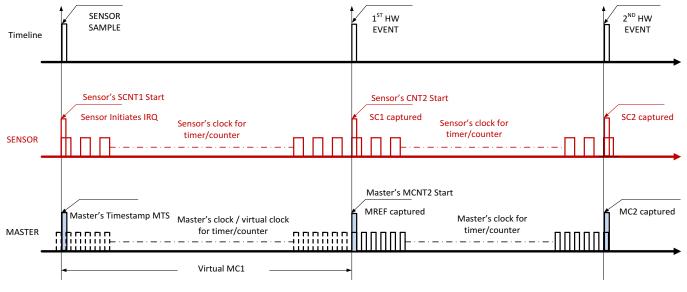


## **Asynchronous Systems and Events**

- Four Async Modes
  - Basic Async Mode 0
  - Enhanced Async Mode 1, 2 and 3
- SETXTIME is the CCC
  - The defining byte selects the running mode



## **Async 0 Time Diagram**



MTS – Master Timestamp, expressed in MASTER's time units

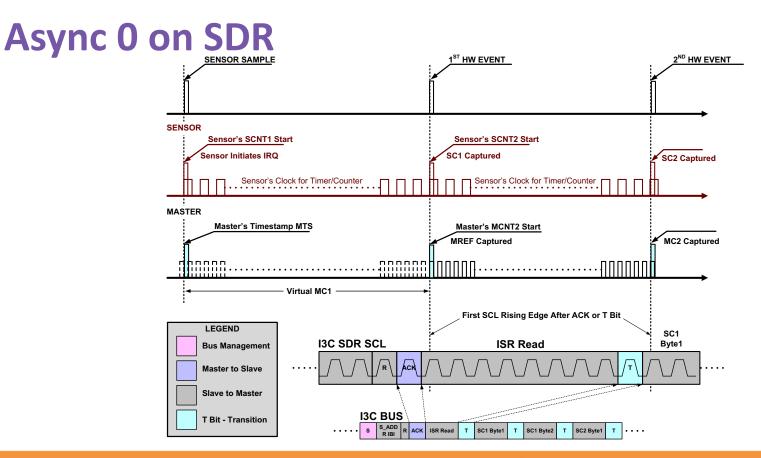
MREF – Master Reference, i.e. Start of Master's secondary counter, MCNT2

MC1, MC2 – Master's counters values, captured at the corresponding HWSE events.

**SC1, SC2** – Slave's counters values, captured at the corresponding HWSE events.

MTS = MREF – MC2×SC1/SC2







# **Elements of Flow Control**

- The Transmitter drives actively the data lines
  - SDA on HDR-DDR
  - SDA and SCL on HDR-TSx

- The Receiver might need to end the transaction
  - The bus needs to provide the opportunity for the Receiver to change the state of a line, in a pre-established way



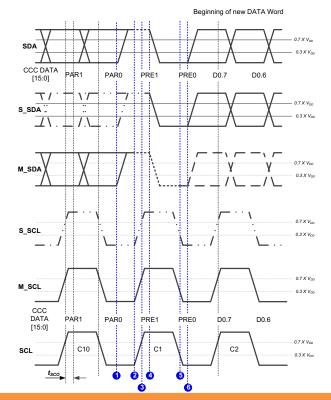
### **HDR-DDR Transactions**

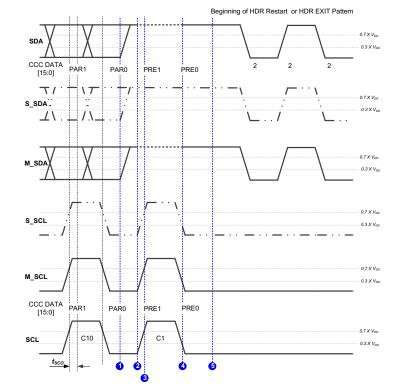
#### **HDR-DDR Preamble Values**

Context	Preamble Value and Interpretation					
	2'b00	2'b01	2'b10	2'b11		
After EnterHDR	Reserved for Future Use	Command Word follows	-	-		
After Read CMD		-	Slave ACK, Data follows	Slave NACK, Aborted		
After Read DATA		CRC Word follows	Master Aborts, Slave yields. Master drives second 0.	Data follows. Master does not drive second bit.		
After Write CMD		-	Data follows	-		
After Write DATA		CRC Word follows	-	Data follows		



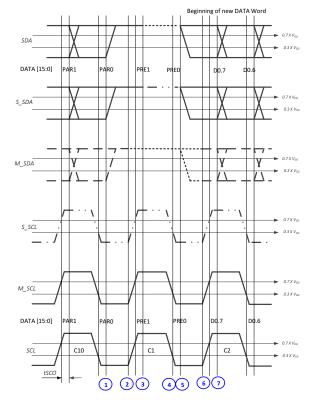
### HDR-DDR – Slave controls DDR READ command

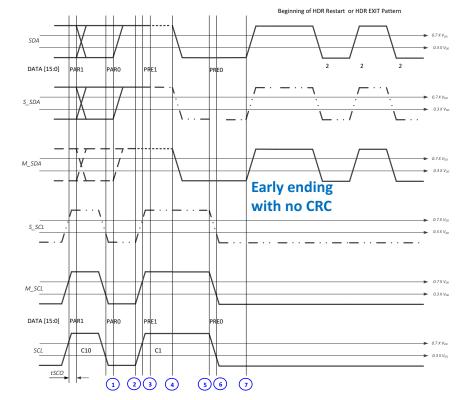






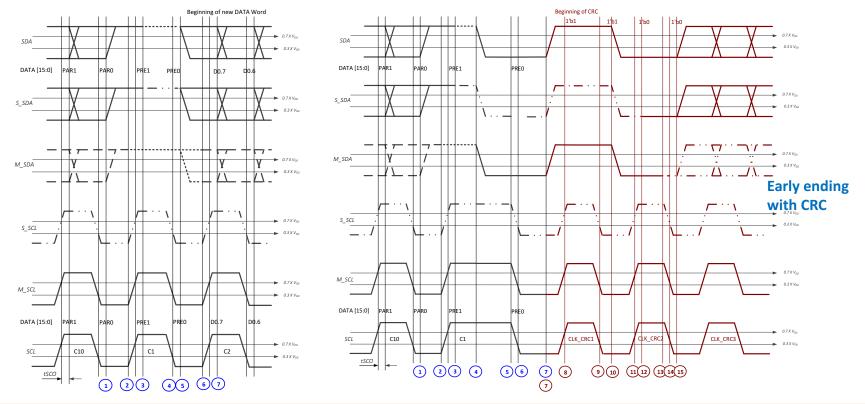
### HDR-DDR – Master Controls DDR READ Transaction [1]







### HDR-DDR – Master Controls DDR READ Transaction [2]





► 0.7 X V<sub>DD</sub>

- 03YV-

► 0.3 X V<sub>DD</sub>

→ 0.7 X V<sub>00</sub>

► 0.3 X Voo

→ 0.7 X V<sub>DD</sub>

- 0.3 X Voo

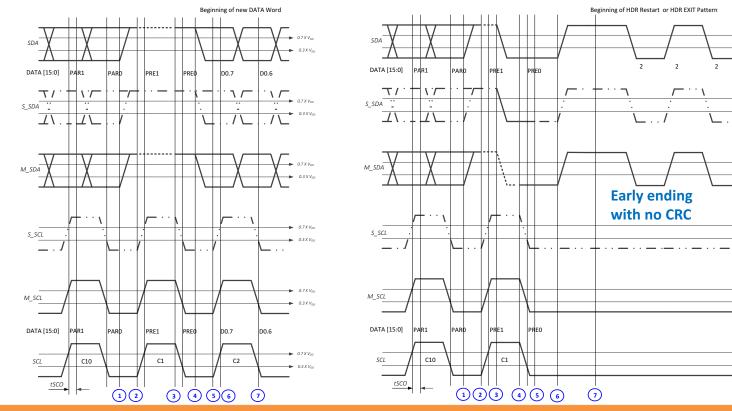
► 0.7 X V<sub>D</sub>

► 0.3 X V<sub>D</sub>

► 0.7 X V<sub>cr</sub>

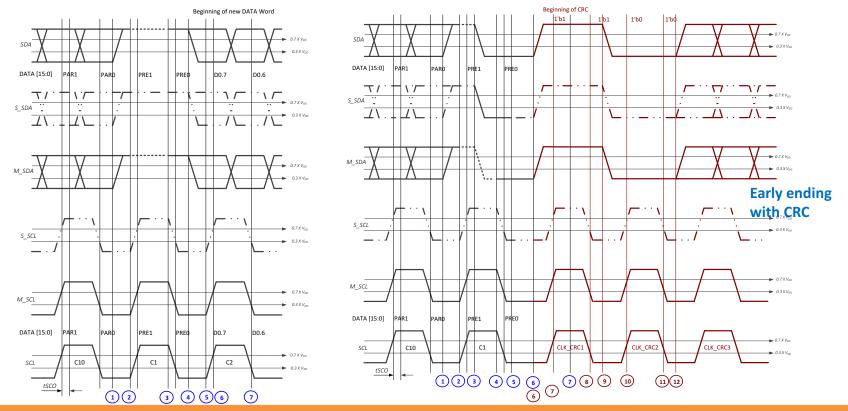
► 0.3 X V<sub>0</sub>

### HDR-DDR – Slave Requests DDR WRITE Termination [1]





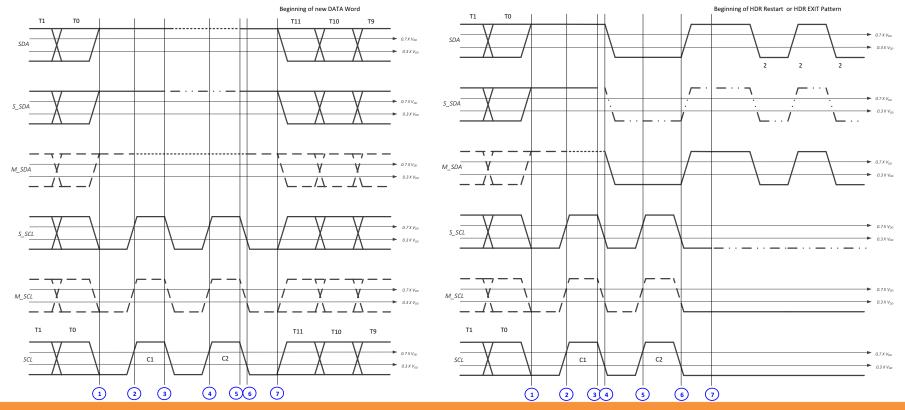
### HDR-DDR – Slave Requests DDR WRITE Termination [2]



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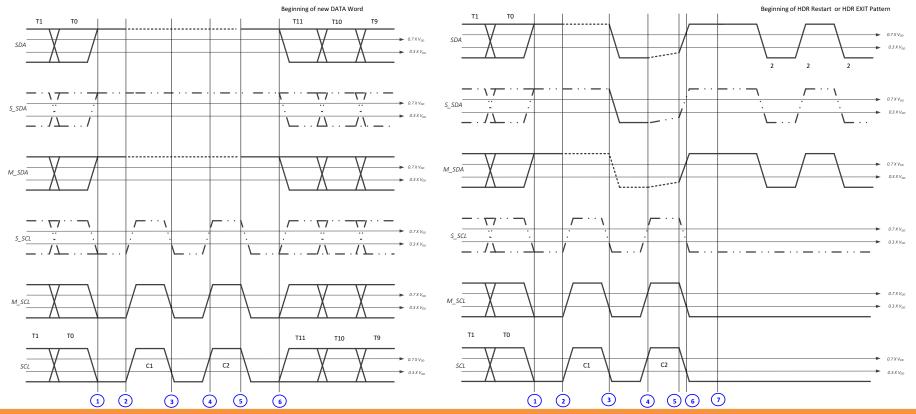
#### HDR-TSx – Master Controls S2M Data Transfer



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#### HDR-TSx – Slave Controls the M2S Data Transfer

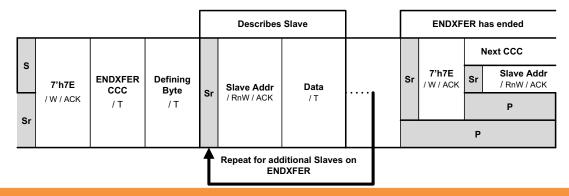




### **ENDXFER CCC – Early Termination Setup and Invocation**

- Defining Bytes
  - 0x7F SET/GET Repetition Interval for HDR-TSx
  - 0x55 Initiates the HDR-TSx with Ending Data Transfer Procedure Enabled
  - 0xF7 SET/GET CRC Index for HDR-DDR
  - 0xAA Initiates the HDR-DDR with Ending Data Transfer Procedure Enabled

S	7'h7E	ENDXFER CCC	Defining Byte	(Optional) Data	Sr
Sr	/ W / ACK	/т	/ T	/ T	Р



# mipi DEVCON THANK YOU

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